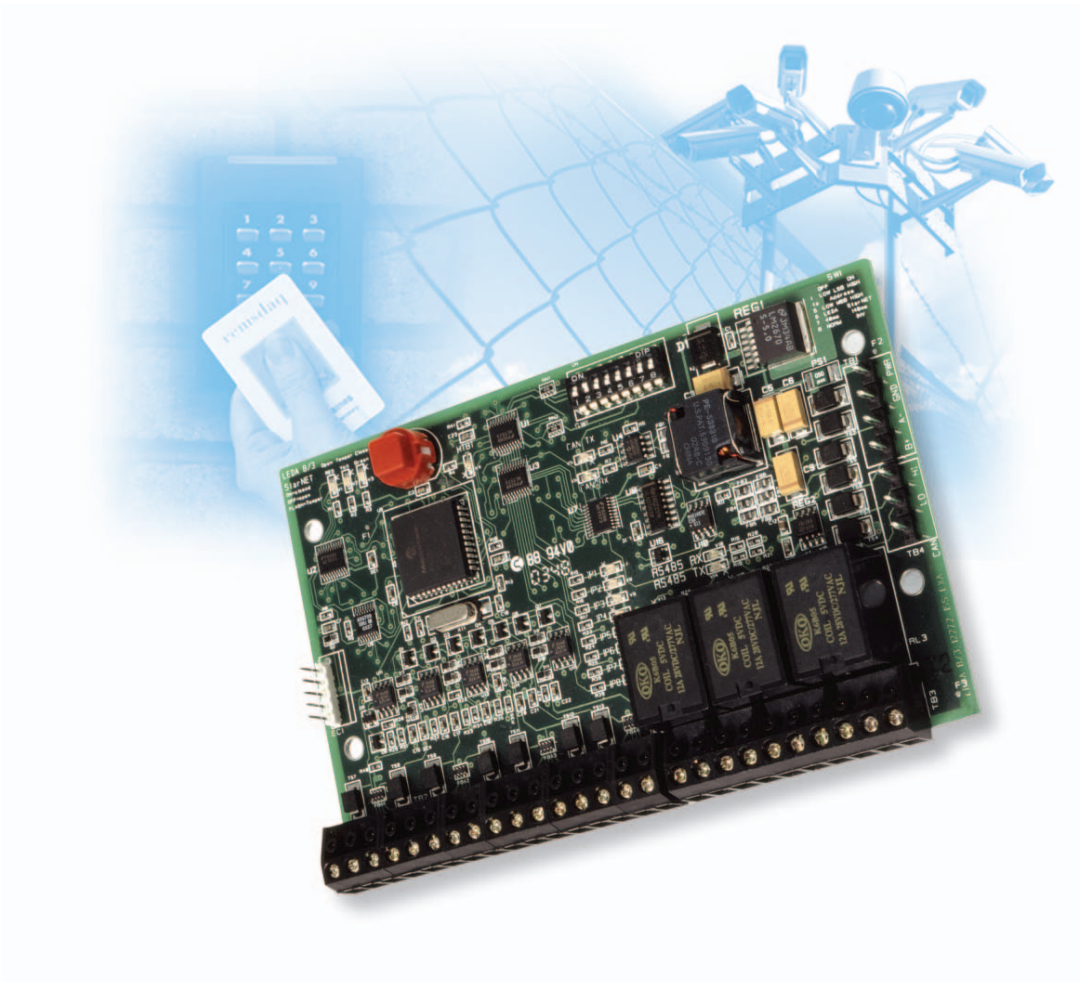


# StarNET

StarNET LEDA 8/3

evolution of proven technology



## FEATURES

- Compact alarm interface unit
- Suitable for distributed PIDS applications
- Supports both CAN and RPI protocols
- Up to 24 supervised inputs (CAN applications only)

The StarNET LEDA 8/3 is a compact alarm interface unit designed to integrate into the Remsdaq StarWatch security management system.

## Remsdaq Part Number 12272

It is housed in its own enclosure and is capable of communicating with either a StarWatch master station, RPI poller or StarNET ACP. The StarNET LEDA is designed as a form, fit and function replacement for the 12056 LEDA 8/3.

Each StarNET LEDA is equipped with:-

- 8 physical supervised alarm inputs.
- Unique 3 into 1 technology provides up to 24 EOL supervised inputs. StarNET ACP only.
- 3 changeover relays.

Up to 31 StarNET LEDA Modules can communicate with either an RPI host (StarGate I/II) or StarWatch master station at distances of up to 1200 m. When connected to a StarNET ACP, 12 units can be supported. The StarNET LEDA communicates with its RPI host at a fixed rate of 9600 baud.

When interfacing to a StarNET ACP host using the CAN bus protocol StarNET LEDA will communicate at 125 Kbits per second at a maximum distance of 400m.

The StarNET LEDA is housed in a compact IP55 enclosure and requires power from a 12 vdc supply.

There are two configuration settings dependent on how the StarNET LEDA is to be used. These are:-

- 8/24 input mode – 24 input mode for StarNET ACP only.
- Station address – required for both applications.

When operating in conjunction with a StarNET ACP, the StarNET LEDA has the ability to connect three alarm inputs to each physical input using special colour coded termination devices. This allows a significant reduction in field wiring, lowers the cost of alarm integration and can still provide individual annunciation of each sensor and its associated tamper alarm.

### Processor

PIC 18F458 Microcontroller running at 40MHz  
32 KBytes of on board Flash memory  
1.5 KBytes of on board RAM  
256 Bytes of EEPROM  
Conforms to the CAN 2.0B spec

### Communications Protocol

RPI (Remsdaq Protocol Interface)  
CAN Bus

### Dimensions

142mm x 89mm – PCB  
170mm x 135mm x 78mm – enclosure

### Power Requirements

External Supply: 10V to 18V DC  
Consumption: 180mA @ 12V DC

### Alarm Input

8 physical supervised alarm input connections  
24 logical supervised alarm input connections  
Special colour coded termination devices

### On-Board Relays

3 changeover (NO/NC)  
Each relay rated at 2A at a DC voltage of 30V

### LED Indications

- LED1 – Physical Input 1
- LED2 – Physical Input 2
- LED3 – Physical Input 3
- LED4 – Physical Input 4
- LED5 – Physical Input 5
- LED6 – Physical Input 6
- LED7 – Physical Input 7
- LED8 – Physical Input 8
- LED9 – logical input status 1,4,7,10 .....22
- LED10 – logical input status 2,5,8,11.....23
- LED11 – logical input status 3,6,9,12.....24
- LED12 – OP1
- LED13 – OP2
- LED14 – OP3
- LED15 – RS485 TX
- LED16 – RS485 RX
- LED17 – Heartbeat
- LED18 – CAN bus TX
- LED19 – CAN bus RX

Please note that in 8 input mode – LEDs 9-11 do not operate.

### Environmental Specification

Operating temperature -40°C to +70°C.  
Storage temperature -40°C to +70°C.

The 12272 operates with a relative Humidity up to 95% (non-condensing) at a temperature of +40°C.

### EMC Requirements

BS EN 55022 Radiated and Conducted Emissions  
BS EN 50082-1 Generic Immunity



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